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SONAR TRANSDUCER WITH TUNING PLATE AND TUNING FLUID

TO ALL WHOM IT MAY CONCERN:

BE IT KNOWN THAT THEODORE J. MAPES, citizen of the United States of America, employee of the United States Government, a resident of Waitsfield, County of Washington, State of Vermont, has invented certain new and useful improvements entitled as set forth above of which the following is a specification.

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1 Attorney Docket No. 76646

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3 SONAR TRANSDUCER WITH TUNING PLATE AND TUNING FLUID

4

5 STATEMENT OF GOVERNMENT INTEREST

6 The invention described herein may be manufactured and used  
7 by or for the Government of the United States of America for  
8 governmental purposes without the payment of any royalties  
9 thereon or therefor.

10

11 BACKGROUND OF THE INVENTION

12 (1) Field of the Invention

13 The present invention is directed to a sonar transducer  
14 with a tuning plate and a tuning fluid having increased maximum  
15 power which may be radiated from a given transducer by  
16 increasing the radiation resistance seen by the transducer. The  
17 present invention also is directed to providing a method for  
18 setting the mechanical resonant frequency of a sonar transducer  
19 above or below the value which is characteristic of the  
20 transducer without the tuning system.

21 (2) Description of the Prior Art

22 In general, the power which may be radiated in a fluid  
23 medium by a transducer is proportional to the product of the  
24 area of the radiating surface, the square of the surface

1 velocity, and the characteristic impedance (sound speed times  
2 fluid density) of the medium. Thus to increase the radiated  
3 power, either the surface area, or the velocity, or both, must  
4 be increased. However, the radiating surface area of a sonar  
5 transducer is usually limited by the requirement to produce a  
6 specific directional characteristic (beam pattern). In  
7 addition, the maximum velocity which may be achieved is limited  
8 by physical constraints on the transduction material, such as  
9 maximum electrical field or maximum mechanical strain.

10 In a sonar transducer in which body stress in the active  
11 transduction material (such as, for example, electrostrictive or  
12 magnetostrictive materials) is used to convert electrical energy  
13 into mechanical energy, the optimum design with respect to power  
14 output and bandwidth is achieved when the characteristic  
15 mechanical impedance (density times sound speed times cross  
16 sectional area) of the transduction material is matched to (i.e.  
17 equals) that of the acoustical load. Since the characteristic  
18 impedance (density times sound speed) of the transduction  
19 material and the fluid medium are inherent material properties,  
20 an attempt to achieve the desired match of the characteristic  
21 mechanical impedances may take the form of a mechanical area  
22 transformation. In the design of a longitudinal vibrator or  
23 tonpilz such an impedance match is often approximated by  
24 employing a piston whose area is much greater than the area of

1 the active transduction material. In particular, the  
2 characteristic impedance of typical piezoelectric ceramic  
3 materials (such as lead zirconate titanate) is in the order of  
4 34,000,000 MKS Rayls, whereas the characteristic impedance of  
5 sea water is about 1,500,000 MKS Rayls. This would indicate an  
6 area ratio of about 23 to 1 to achieve the optimum match of the  
7 characteristic mechanical impedance. The dimensions of the  
8 radiating piston are generally dictated by directivity  
9 considerations, leaving only the area of the ceramic as a design  
10 variable. However, use of an area ratio of 23 to 1 would result  
11 in a very fragile ceramic configuration. Other considerations,  
12 such as withstanding hydrostatic pressure and explosive shock,  
13 dictate that the maximum practical area ratio is in the order of  
14 6 to 1. This results in about a 4 to 1 mismatch between the  
15 sonar transducer and the fluid medium. For these reasons, it  
16 has never been possible to achieve a perfect match.

17

#### 18 SUMMARY OF THE INVENTION

19 Accordingly, it is an object of the present invention to  
20 provide a method for designing a transducer so that the  
21 radiation resistance seen by the transducer is increased to  
22 facilitate higher power output.

1 It is a further object of the present invention to provide  
2 a method for designing a sonar transducer having a mechanical  
3 resonant frequency which may be decreased or increased.

4 It is still a further object of the present invention to  
5 provide a smaller, lighter sonar transducer.

6 The foregoing objects are achieved by the method and the  
7 sonar transducer of the present invention.

8 In accordance with the present invention, a method for  
9 maximizing the radiated power of a transducer broadly comprises  
10 the steps of providing a transducer system comprising a  
11 transducer operating at a frequency  $f$  and having a face, a  
12 tuning fluid medium having a density of  $\rho_1$  and a speed of sound  
13  $c_1$ , a tuning plate having a density  $\rho_p$  and a thickness  $t$  spaced a  
14 distance  $s$  from the transducer face, and an external fluid  
15 medium having a density  $\rho_2$  and a speed of sound  $c_2$ ; and tuning  
16 the transducer by choosing  $\rho_p, t$ , and  $s$  so that

$$\tan\left(2\pi f \frac{s}{c_1}\right) = \frac{\rho_1 c_1}{2\pi f \rho_p t} \quad (1)$$

18 Further, in accordance with the present invention, a method  
19 for changing the resonance frequency of a transducer is  
20 provided. The method comprises the steps of providing a  
21 transducer system having a transducer with a face and an  
22 operating frequency  $f$ , a tuning plate spaced from the transducer

1 face by a distance  $s$ , and a fluid medium between the transducer  
 2 face and the tuning plate having a density  $\rho_1$  and a speed of  
 3 sound  $c_1$ ; and decreasing the resonance frequency if the  
 4 expression below is positive or increasing the resonance  
 5 frequency if it is negative.

$$6 \quad \rho_1 c_1 \cot \left( 2\pi f \frac{s}{c_1} \right) \quad (2)$$

7 The present invention also relates to a transducer system  
 8 for use on a vehicle traveling through an external fluid medium  
 9 having a density  $\rho_2$  and a speed of sound  $c_2$ . The transducer  
 10 system broadly comprises a transducer having a radiating face  
 11 and an operating frequency  $f$ , rigid wall means for positioning  
 12 the transducer relative to an exterior wall of the vehicle, a  
 13 tuning plate for separating the transducer from the external  
 14 medium, which tuning plate has a density  $\rho_p$  and a thickness  $t$  and  
 15 being spaced from the radiating face by a distance  $s$ , and a  
 16 tuning fluid positioned intermediate the tuning plate and the  
 17 radiating face, which tuning fluid has a density  $\rho_1$  and a speed  
 18 of sound  $c_1$ . The system has a complex specific acoustical  
 19 impedance at the radiating face in accordance with the equation:

$$20 \quad Z(s, f) = \left[ \frac{(2\pi f \rho_p t)^2}{\rho_2 c_2 \rho_1 c_1} + \frac{\rho_1 c_1}{\rho_2 c_2} \right] \rho_1 c_1 + i \rho_1 c_1 \cot \left( 2\pi f \frac{s}{c_1} \right) \quad (3)$$

1 Other details of the sonar transducer with tuning plate and  
2 tuning fluid of the present invention, as well as other objects  
3 and advantages attendant thereto, are set forth in the following  
4 detailed description and the accompanying drawings wherein like  
5 reference numerals depict like elements.

#### 7 BRIEF DESCRIPTION OF THE DRAWINGS

8 The Figure illustrates a configuration of a sonar  
9 transducer system in accordance with the present invention.

#### 11 DESCRIPTION OF THE PREFERRED EMBODIMENT(S)

12 Referring now to the Figure, a system 10 containing a  
13 sonar transducer 12 is illustrated. The sonar transducer 12 is  
14 a piston type transducer having a radiating piston 14. The  
15 sonar transducer 12 is mounted to a rigid walled sea chest 18  
16 which is incorporated into a hull 20 of a vessel such as an  
17 ocean going vessel. An acoustical window 16 separates the  
18 interior of the sea chest 18 from an external fluid medium 26.  
19 In a nautical setting, the external fluid medium 26 is sea-  
20 water. The acoustical window 16 comprises a thin tuning plate  
21 which may be formed from a metal such as stainless steel, a  
22 reinforced plastic such as fiberglass, or an elastomeric  
23 material such as polyurethane or rubber. The space 24 bounded  
24 by the sonar transducer 12, the walls of the sea chest 18, and



1 the acoustic window 16 is filled with a tuning fluid 22. The  
2 tuning fluid 22 may be castor oil, silicone fluid, glycerin,  
3 kerosene, or any other suitable medium.

4 In the system 10, the ratio  $R_1$  of the characteristic  
5 impedance of the transduction element to the characteristic  
6 impedance of the external fluid medium 26 is greater than 1; the  
7 ratio  $R_2$  of the area of the radiating piston 14 to the area of  
8 the transduction element is less than  $R_1$ ; and the system is  
9 configured so that the effective specific radiation resistance  
10 presented to the transducer piston 14 by the tuning fluid 22,  
11 i.e. the real part of  $Z(s,f)$  calculated using equation 1 below,  
12 is approximately  $R_1/R_2$  times the characteristic impedance of  
13 fluid 26.

14 The present invention provides a means and a method for  
15 increasing the magnitude of the effective radiation resistance  
16 presented to the transducer 12 by the medium, thus increasing  
17 the radiated power for a given surface area and velocity.

18 The important factors in the embodiment of the Figure are  
19 as follows: (a) the thickness and density of the acoustical  
20 window or tuning plate 16; (b) the distance  $s$  from the tuning  
21 plate 16 to the face 28 of the piston 14; (c) the characteristic  
22 impedance (sound speed times density) of the tuning fluid 22;  
23 and (d) the characteristic impedance of the external fluid  
24 medium 26.

1        The complex specific acoustical impedance at the radiating  
2        face 28 of the sonar transducer 12 for the system 10 shown in  
3        the Figure may be described by the following equation:

$$4 \quad Z(s,f) = \left[ \frac{\rho_2 c_2 - i \left( 2\pi f \rho_p t + \rho_1 c_1 \tan \left( 2\pi f \frac{s}{c_1} \right) \right)}{\rho_1 c_1 - 2\pi f \rho_p t \tan \left( 2\pi f \frac{s}{c_1} \right) - i \rho_2 c_2 \tan \left( 2\pi f \frac{s}{c_1} \right)} \right] \rho_1 c_1 \quad (4)$$

5        where:

6         $c_1$  is the sound speed in the tuning fluid 22 in meters per  
7        second;

8         $\rho_1$  is the density of the tuning fluid 22 in kilograms per cubic  
9        meter;

10        $c_2$  is the sound speed in the external fluid medium 26 in meters  
11       per second;

12        $\rho_2$  is the density of the external fluid medium 26 in kilograms  
13       per cubic meter;

14        $\rho_p$  is the density of the acoustic window or tuning plate material  
15       in kilograms per cubic meter;

16        $t$  is the thickness of the acoustic window or tuning plate in  
17       meters;

18        $f$  is the operating frequency, Hertz;

19        $s$  is the distance from the transducer radiating piston 14 to the  
20       acoustic window or tuning plate 16 in meters; and

i is the imaginary number equal to the square root of negative one.

Three possible tuning methods are described hereinafter:

(a) tuning by means of the tuning plate 16 in combination with the tuning fluid 22; (b) tuning by means of the tuning plate 16 alone; and (c) tuning by means of the tuning fluid 22 alone.

Consider the denominator of equation 4, when the values of the variables are such that

$$\tan\left(2\pi f \frac{s}{c_1}\right) = \left(\frac{\rho_1 c_1}{2\pi f \rho_p t}\right) \quad (5)$$

the real term in the denominator vanishes. Since the operating frequency  $f$  is generally specified, this constraint is achieved by the proper selection of spacing  $s$ , tuning plate density  $\rho_p$  and thickness  $t$ , and the tuning fluid characteristic impedance  $\rho_1 c_1$ .

When the constraint indicated in equation 2 is satisfied, equation 4 reduces to:

$$Z(s, f) = \left[ \frac{(2\pi f \rho_p t)^2}{\rho_2 c_2 \rho_1 c_1} + \frac{\rho_1 c_1}{\rho_2 c_2} \right] \rho_1 c_1 + i \rho_1 c_1 \cot\left(2\pi f \frac{s}{c_1}\right) \quad (6)$$

The first term in equation 6 describes the specific acoustic resistance at the face of the transducer 12, and the second (imaginary) term represents the specific acoustic reactance. The resistive component may be optimized to achieve the desired radiated power and the reactive component may be set

1 to increase or decrease the resonance frequency of the  
2 transducer 12.

3 In the event that the tuning fluid 22 and the external  
4 fluid medium 26 are identical, which would be the case, for  
5 example, if the sea chest is free-flooded, then  $\rho_1 c_1 = \rho_2 c_2$  and  
6 the complex impedance is given by

$$7 \quad Z(s, f) = \left[ \left( \frac{2\pi f \rho_p t}{\rho_2 c_2} \right)^2 + 1 \right] \rho_2 c_2 + i \rho_2 c_2 \cot \left( 2\pi f \frac{s}{c_2} \right) \quad (7)$$

8 In this example, the radiation resistance may be increased  
9 over the characteristic impedance by choosing appropriate values  
10 of  $\rho_p$  and  $t$ . For instance, to make the radiation resistance four  
11 times the value of  $\rho_2 c_2$ , one sets

$$12 \quad \left( \frac{2\pi f \rho_p t}{\rho_2 c_2} \right)^2 + 1 = 4 \quad (8)$$

13 and find that the solution is

$$14 \quad \rho_p t = \frac{\sqrt{3} \rho_2 c_2}{2\pi f} \quad (9)$$

15 Thus any tuning plate 16 whose product of density times

16 thickness equals  $\frac{\sqrt{3} \rho_2 c_2}{2\pi f}$  will meet the requirement. The spacing

17 from the sonar transducer to the tuning plate for this design is  
18 computed from:

$$19 \quad s = \frac{c_2}{2\pi f} \arctan \left( \frac{\rho_2 c_2}{2\pi f \rho_p t} \right) \quad (10)$$

1 Tuning may also be achieved by the selection of the proper  
 2 tuning fluid 22. In this approach, the acoustic window or  
 3 tuning plate 16 is replaced by a thin membrane of negligible  
 4 density per unit area (the product of density times thickness).  
 5 For this approach, either  $\rho_p$  or  $t$  is set to equal to 0 in  
 6 equation 4 with the result:

$$7 \quad Z(s,f) = \left[ \frac{\rho_2 c_2 - i \rho_1 c_1 \tan\left(2\pi f \frac{s}{c_1}\right)}{\rho_1 c_1 - i \rho_2 c_2 \tan\left(2\pi f \frac{s}{c_1}\right)} \right] \rho_1 c_1 \quad (11)$$

8 Now if the spacing  $s$  in equation 11 is adjusted so that  $s =$   
 9  $c_1/4f$ , or any odd multiple thereof, the impedance at the  
 10 transducer will be:

$$11 \quad Z = \rho_2 c_2 \left( \frac{\rho_1 c_1}{\rho_2 c_2} \right)^2 \quad (12)$$

12 That is, the characteristic impedance of the external fluid  
 13 medium 26 times the square of the ratio of characteristic  
 14 impedances of the two fluids 22 and 26. If, for example, the  
 15 tuning fluid 22 is glycerin and the external fluid medium 26 is  
 16 sea water, the radiation resistance will be increased by a  
 17 factor of 2.37, that is,

$$18 \quad Z = (2.37) \rho_2 c_2 \quad (13)$$

19 The present invention has numerous advantages. For  
 20 example, the radiation resistance of a fluid medium may be

increased over its plane wave value, permitting greater output power for a specified velocity from a sonar transducer. Further, the mechanical resonant frequency of a sonar transducer may be increased or decreased by an appropriate choice of tuning plate material, dimensions, and spacing and coupling fluid 22. A smaller, lighter sonar transducer may be designed to achieve a required level of output power using the principles disclosed herein.

Many alternative configurations to the suggested practical embodiment of the Figure may be designed to take advantage of the principles of acoustical tuning. These include, for example, incorporating the acoustical tuning system as an integral part of a sonar transducer design. In this approach, the sonar transducer, enclosure (sea chest), tuning fluid, and tuning plate may be configured as a self-contained, integral unit.

Large sonar arrays comprised of a multiplicity of acoustically tuned transducers may be designed for increased output power and beamforming capability.

The theoretical model of this disclosure is predicated on plane wave propagation generated by a rigid circular piston. However, the principles are easily applied to a cylindrical transducer geometry, in which a radially propagating cylindrical wave is generated. In such a design, the system would be co-

1 axial with the cylindrical axis of the transducer, and the  
2 tuning plate would be replaced with a thin walled concentric  
3 tuning tube or cylinder. The tuning fluid would occupy the  
4 space between the cylindrical transducer and the tuning tube.

5 The mechanical resonant frequency of the tuned transducer  
6 may be set above or below the value of the untuned transducer.

7 It is apparent that there has been provided in accordance  
8 with the present invention a sonar transducer with tuning plate  
9 and tuning fluid which fully satisfies the objects, means, and  
10 advantages set forth hereinbefore. While the present invention  
11 has been described in the context of specific embodiments  
12 thereof, other alternatives, modifications, and variations will  
13 become apparent to those skilled in the art having read the  
14 foregoing description. Accordingly, it is intended to embrace  
15 those alternatives, modifications and variations as fall within  
16 the broad scope of the appended claims.

**CLAIMS NOT INCLUDED**

**PAGES 15 - 21**



2  
3 SONAR TRANSDUCER WITH TUNING PLATE AND TUNING FLUID

4  
5 ABSTRACT OF THE DISCLOSURE

6 A method for maximizing the radiated power of a transducer,  
7 such as a sonar transducer, includes providing a transducer  
8 system comprising a transducer operating at a frequency  $f$  and  
9 having a radiating face, a tuning fluid having a density  $\rho_1$  and a  
10 speed of sound  $c_1$ , a tuning plate having a density  $\rho_p$  and a  
11 thickness  $t$ , and an external fluid having a density  $\rho_2$  and a  
12 speed of sound  $c_2$ ; and tuning the transducer to have a maximum  
13 specific acoustic resistance at the radiating face in accordance

14 with the equation:  $\left[ \frac{(2\pi f \rho_p t)^2}{\rho_2 c_2 \rho_1 c_1} + \frac{\rho_1 c_1}{\rho_2 c_2} \right] \rho_1 c_1$ . The present invention

15 also relates to changing the resonance frequency of a transducer  
16 including providing a transducer system with an operating  
17 frequency  $f$ , the tuning plate spaced from the transducer face by  
18 a distance  $s$ , and the tuning fluid between the transducer face  
19 and the tuning plate and changing the resonance frequency in

20 accordance with the equation  $\rho_1 c_1 \cot \left( 2\pi f \frac{s}{c_1} \right)$ .

